

The Epic Struggle

Sci vs. ID



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History

SASI

SMD-E

ATA

ESDI

IDE

ST506

SCSI

History

• PC Revolution of the 1980's

Several disk drive interfaces make their debut:

- SMD, SMD-E
- ESDI
- ST506 ==> IDE

As these evolved, Controller functionality was moved from the Host Adapter to the Drive.

Standards lead to interoperability.

- SASI ==> SCSI

• SCSI & IDE...

are managed by the same standards body:

- SCSI ==> **T10**
- ATA ==> **T13**

IDE = Integrated Drive Electronics

ATA = AT Attachment

SCSI = Small Computer Systems Interface



History

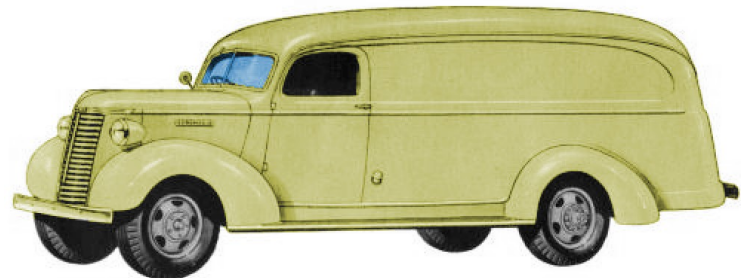
IDE (ATA) only supports disk drives

- One-bit bus address space (master/slave)



SCSI has a wider command set

- Bus address space depends on SCSI version (minimum 4-bit)
- Multiple Logical Units (LUs or LUNs) per target
- Support for:
 - CD-Rom Drives
 - Tape Robots and Drives
 - More stuff



History

Just to confuse things:

ATAPI = ATA with Packet Interface

- SCSI commands can be wrapped inside ATAPI commands
- Devices other than disk drives can be controlled (e.g., ATAPI CD-ROM/DVD drives)

This brings up an interesting point:

ATA and SCSI commands carried over other transports

- Fibre Channel == SCSI over Fiber (**T11**)
- iSCSI == SCSI over TCP/IP (IETF)
- ATAoE == ATA over Ethernet (Coraid Corp.)

 The current ATA specification is ATA/ATAPI-7.

 The current SCSI specification is SCSI-3.

The Differences



Difference: Marketing



Personal Storage

- Consumer Prices
 - “Low cost dominates the design^[2]”
- Commodity Parts
 - Simple to buy and to replace
- Individual operation
 - Generally used one at a time, not in groups

Enterprise Storage

- Enterprise Prices
 - Customers willing to pay for higher reliability and performance
- Multiuser / Multi-disk environments
 - Server Farms and Disk Arrays
- I/O tends to be more random
 - Small chunks of larger objects



Difference: Performance vs. Capacity

Higher rotational speed means lower latency

- Smaller platter sizes support faster spindle speeds & lower seek time
- More platter mass means more energy used

More platters provide higher capacity

- Increased spindle mass requires more power to spin
- Increased actuator mass slows down seeks

Higher bus bandwidth improves throughput

- Increased complexity to disk-side electronics

There are always trade-offs.



Difference: Reliability

Environmental Hazards

- Servers and Large Arrays
 - Adjacent drives annoy one another with vibrations
 - Heat
 - 24x7 operation
 - “Hot spindle” rebuilds
- Desktop Systems
 - On/Off operation
- Laptops
 - Shock

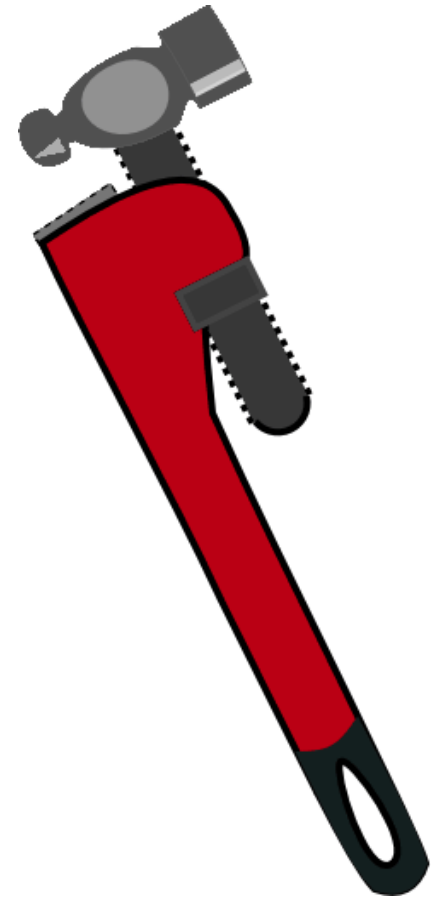


Harsher environments create a requirement for higher-quality parts in order to maintain reliability.

Difference: Protocol

SCSI vs. ATA Command Sets

- SCSI
 - Supports many devices (including graphics!?)
 - Designed for many-to-many operation
 - Robust Diagnostics
- ATA
 - Handles disk drives only
 - Very limited address space (master/slave, no LUNs)
 - Designed for one-to-one or one-to-two operation
 - Limited Diagnostics



It's all about choosing the right tool for the job.

Difference: Price



- Enterprise Drives

- More expensive electronics
- Lower capacity, higher performance
- Better protected (against heat, vibration)
- Longer-lasting parts
- New features introduced to meet customer demand

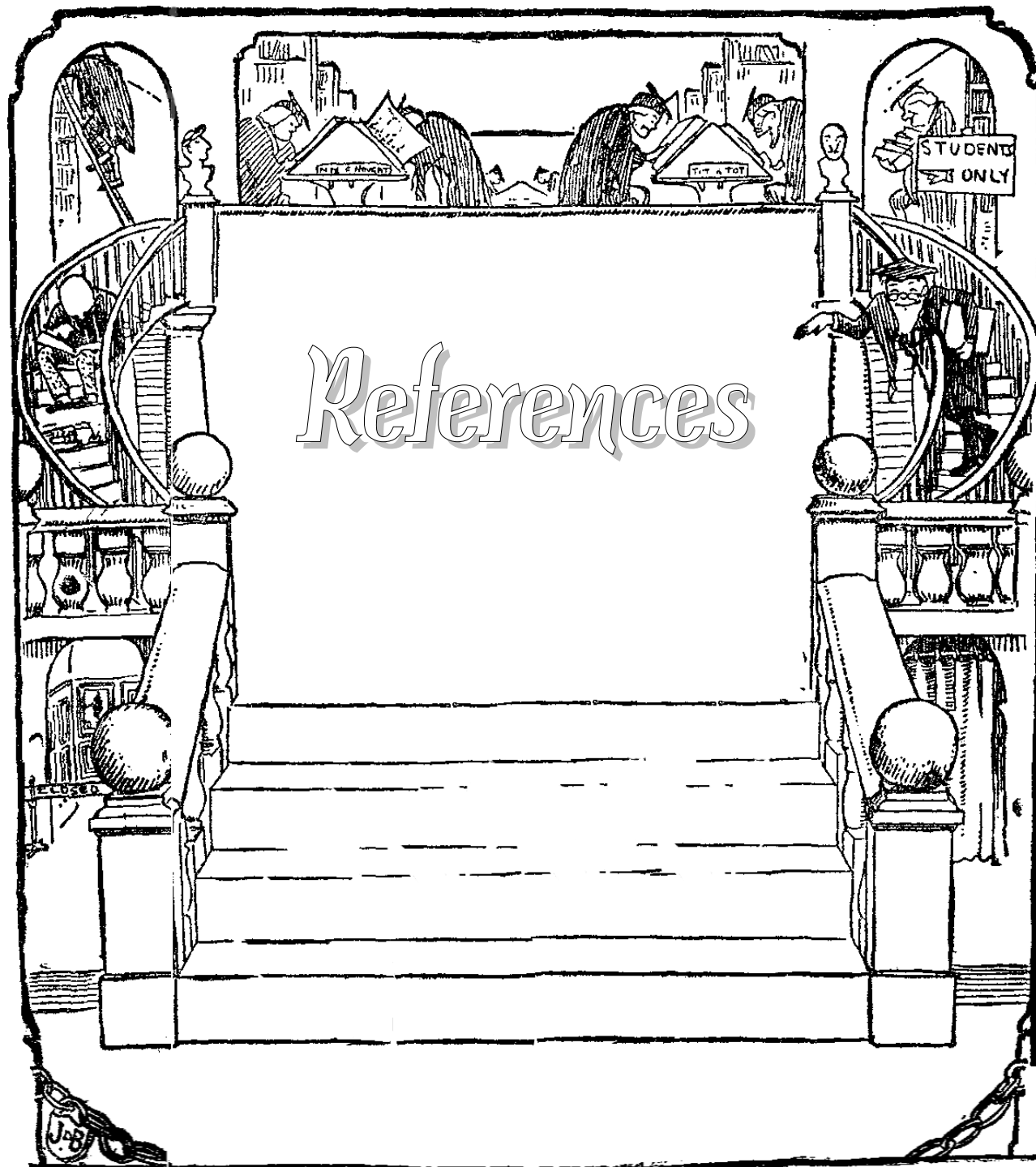
- Personal Drives

- Cheap electronics
- Higher capacity, lower performance
- Commodity parts
- Trickle-down technology

The interface is only one difference.



(my cat)



References

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